

# I-ImaS

CTI:

Summary of patent-related issues regarding  
Image Analysis and Controller Logic

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## Work on Image Analysis and On-Line Control:

1. List of "good" texture extractors using 1<sup>st</sup>-order image statistics  
(report D.8, Amsterdam/04, London/04, Oslo/05)
2. Input Pre-processing Options: Gamma Correction (Oslo/05)
3. General Options for On-Line Control: "Simplistic", "Fully-Adaptive", "Model-Matching" (report D.9, Oslo/05)
4. Image Distortion/Restoration Models (Athens/05)
5. Overview of On-Line Processing "Pipeline" Assembly of Modules, Calibration Templates and Procedures (Athens/05)
6. Advanced Machine Learning Models for Customizable On-Line Control, Operational Profiles, "Reactive" and "Anticipatory" Implementations (Trieste/06)

### Question:

*Which of the above are desirable and suitable as claims within the context of a "universal" patent for the complete I-ImaS system?*

## Identification of suitable texture extractors:

### Best feature functions (final):

- F01: “MIN”
- F02: “MAX”
- F03: “MEAN”
- F07: “POWER”
- F11: “VOLUME”
- SF19: (normalized power)
- SF20: (normalized exposure)

### Additional candidate feature functions (with pre-processing):

- STDEV:  $g < 1.00$
- SURFACE:  $g < 1.00$
- SF17 (norm.surface):  $g < 1.00$
- SF14 (mean.var): exp.decr. response

### Current Status:

1. SINTEF has already conducted simulations for a simple control model, using a single (combined) input feature that implements a version of F01 and F02.
2. Results have shown that such an adaptive control can indeed produce the desired effects for the I-ImaS claims of on-line exposure control.
3. True performance depends on the sophistication of the final implementation in terms of: (a) number of textural features, (b) control model sophistication

*(See: report D.8, Amsterdam/04, London/04, Oslo/05)*

## Summary of Adaptive Controller Profiles:

- Optimal Operational Profile (OOP): Use **different modes of operation**, namely for areas where tissue is or is not detected via specific textural features (e.g. SD).
- Optimal Response Profile (ORP): Use specific **quality templates, asserted by human experts**, for quantifying the notion of desired/optimal response by the controller.
- Optimal Control Profile (OCP): Implement a flexible adaptation model that exploits the current scout scan and internal logic/memory, in order to produce a good estimation of the best way to **optimize the current image quality/dose index**.

### Current Status:

- OOP and OCP have been addressed in D.8 and D.9 reports. ORP requires experts' evaluation sheets on new images acquired from I-ImaS sensors.

*(See: report D.9, Oslo/05)*

## Design of the desired system response (OCP):

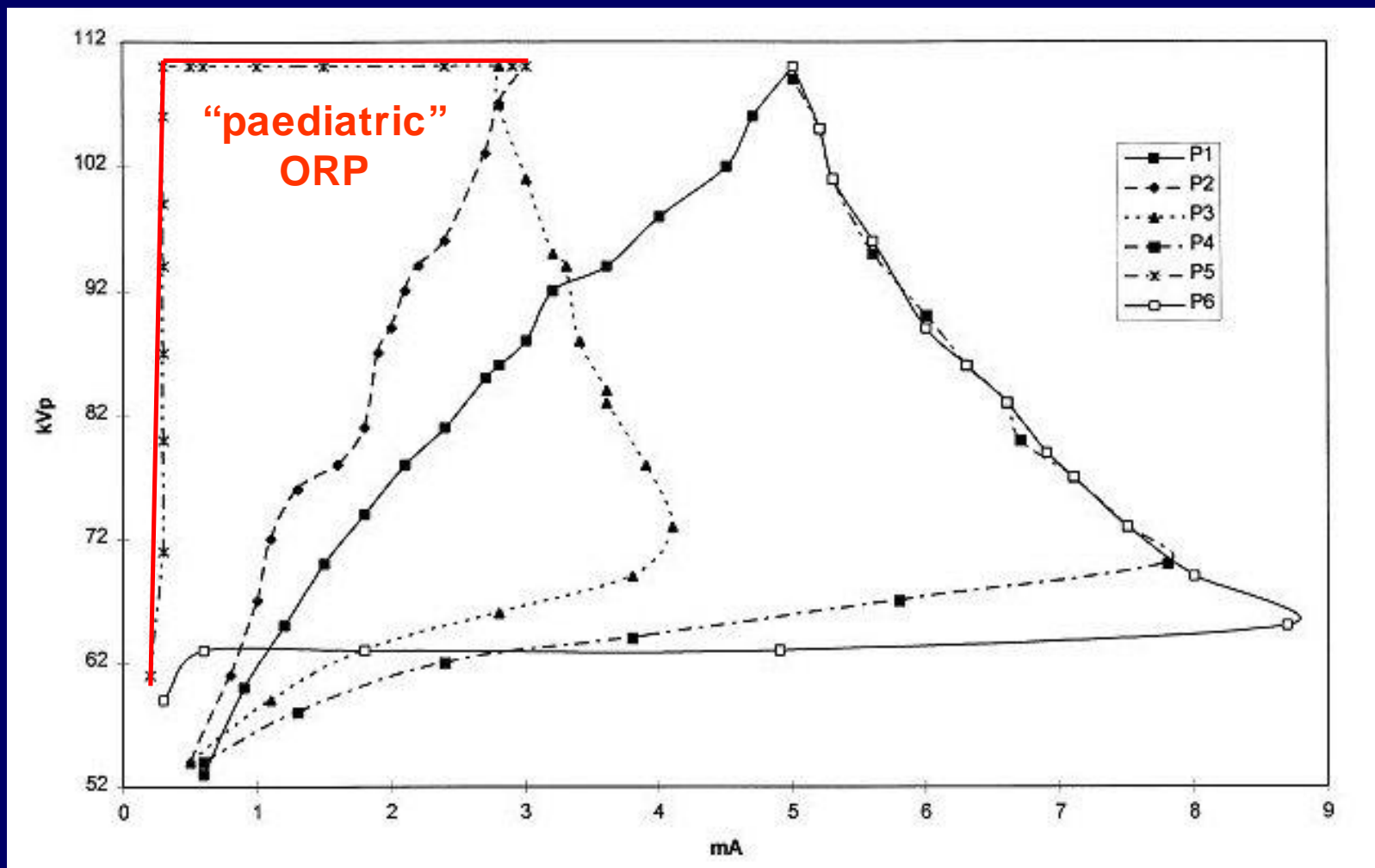
- ▶ **“Simplistic”** : Easy to implement, provided a straight-forward “behavioral” design is evident for mapping feature vectors (states) into regions of optimal or near-optimal image quality (output). Feedback is calculated by means of reverse-mapping between image quality index and input.
- ▶ **“Fully adaptive”** : Does NOT depend on any type of embedded “prior knowledge” from experts and adaptation is local (iterative). However, it needs a minimum of 2-3 consecutive measurements at different states.
- ▶ **“Model matching”** : Prior “template” map is used as guideline for the image quality index space embodying the experts’ knowledge (response). Feedback is calculated directly for either local or global optimization.

Note: Details are included in the D.9 report (Mar.2005)

### Current Status:

- “Simplistic” option has been tested successfully, but dose considerations require an extension into the “Model-Matching” option (combined quality index).

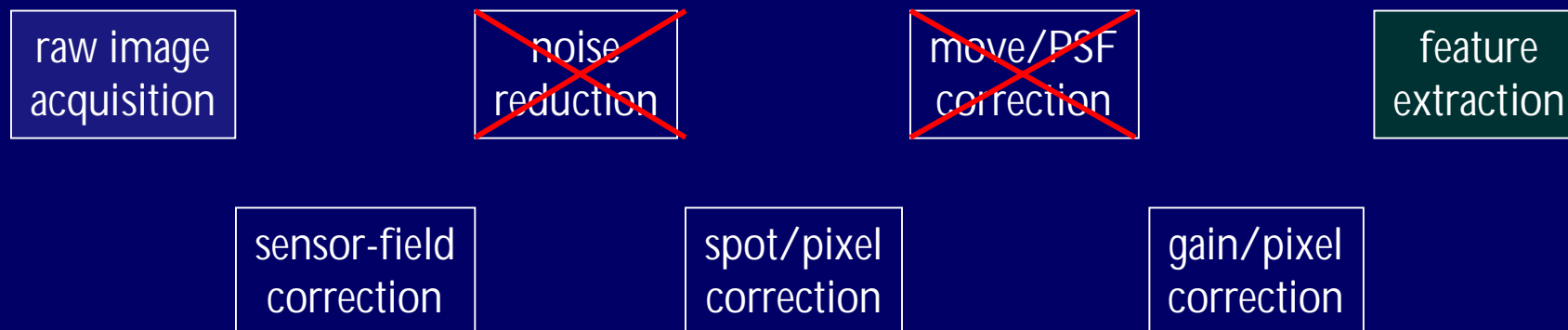
## Example of ORP: Standard AERC curves (fluoroscopic)



Standard kVp/mAs exposure profiles (AERC) for a modern fluoroscopic unit [11].

P1: std 5 mA, P2: std 3 mA, P3: 4 mA high contrast, P4: 8 mA high contrast, P5: “paediatric”, P6: “iodine”

## Overview of image distortion / restoration stages:

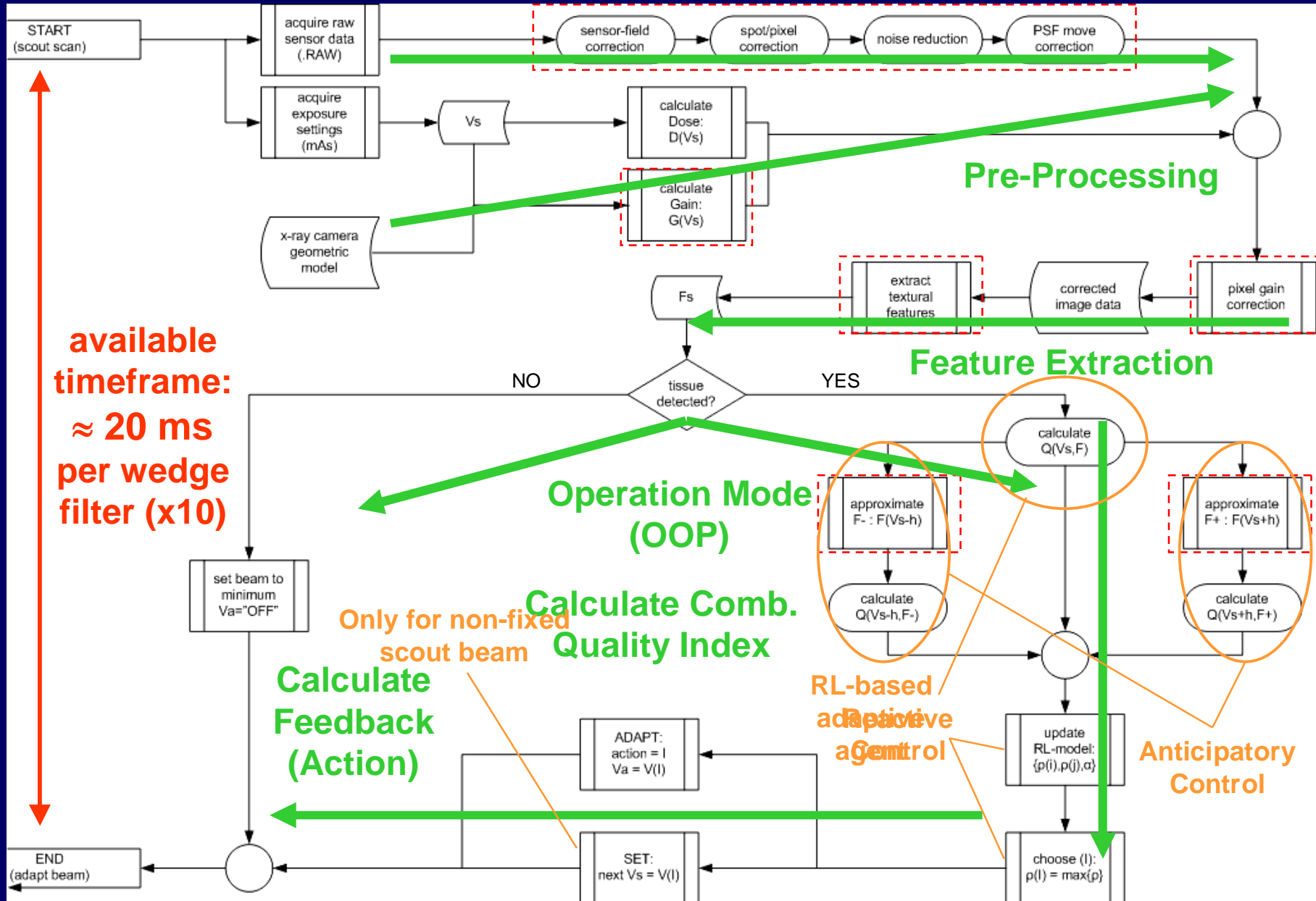


- Different stages embed different levels of complexity and processing time
- Exact ordering and sequence of the stages IS important for optimum results
- Ideal case: feature extraction comes after the last restoration stage
- Real case: embed as many stages as possible within the on-line loop

### Current Status:

- Analytical models have already been studied, but intensive processing stages have to be dropped from the on-line loop.
- Test images from the I-ImaS sensors will determine the necessity of each of the individual restoration stages.

*(See: report D.9, Oslo/05)*





## Design of the desired system response:

Summary of I-ImaS Models for On-Line Control	Reactive Control (error-based)	Reactive Control (error-based)	Reactive Control (error-based)	Anticipatory Control (predictive)
	<i>Intelligence Level</i>			
	<i>Estimated Complexity</i>			
<b>Direct</b> Single-step analytical solution	<b>1</b> SINTEF model test/verified (see: report D.5)	<b>2</b> SINTEF model, with dynamic limits and rules (?) <b>1+</b>	<b>5</b> Weighted Linear Model gain-directed <b>4</b> (see: report D.9)	<b>12</b> Weighted Linear Model gain-directed <b>20</b> (see: Trieste/06)
<b>Iterative</b> Multi-step analytical solution	Small-step adjustments (?)	Gradient-based algorithms (?)	Gain-directed gradient-based algorithms (?)	Gain-directed gradient-based algorithms (?)
<b>Heuristic</b> Behavioral model (on-line learning)	---	---	<b>13</b> Reinforcement Learning Model error-based <b>9</b> (see: Trieste/06)	<b>30</b> Reinforcement Learning Model predictive <b>27</b> (see: Trieste/06)

## Remaining phases of work for I-ImaS "intelligence":

Images from  
I-ImaS sensors

Dose  
Measurements

Statistical  
Analysis

Evaluation  
from Experts

Required  
Pre-Processing

Texture-to-Quality  
Linear Model

Combined Index  
(Quality+Dose)

Calibration  
Protocols

OOP

OCP

ORP

Final I-ImaS  
Image Analysis

Final I-ImaS  
Adaptive Control

## Suggestive References:

- [21] “I-ImaS, Workpackage 3, “Update on current progress and preliminary results for the on-chip processing”, presentation for 2nd I-ImaS meeting, Amsterdam, 26-27 May, 2004.
- [23] *I-ImaS, Workpackage 3 – Deliverable D.8*, “Translating information signatures to a sequence of well-defined processing functions”, Feb.2005
- [24] *I-ImaS, Workpackage 3*, “Update on current progress and report for deliverable D.8”, CTI presentation for 3rd I-ImaS meeting, London, 12-13 Oct 2004
- [25] *I-ImaS, Workpackage 3 – Deliverable D.9*, “Different approaches to providing intelligence to the sensor/imaging system”, Mar.2005
- [26] *I-ImaS, Workpackage 3*, “Update on current progress and deliverable report D.8”, CTI presentation for 4th I-ImaS meeting, Oslo, 14-15 Feb 2005
- [29] *I-ImaS, CTI*, “Top-level system designs”, Mar.2005
- [34] *I-ImaS*, “Enhancements to the image pre-filtering and image restoration options, and preface to x-ray camera geometry”, CTI presentation for 5th I-ImaS meeting, Athens, 29-30 Sept 2005.
- [35] *I-ImaS*, “Improved Adaptive Control by Anticipatory and Reinforcement-Learning options for the I-ImaS Controller Logic”, CTI presentation for 6th I-ImaS meeting, Trieste, 10-11 Jan 2006.